F08NUF (CUNMHR/ZUNMHR) – NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

F08NUF (CUNMHR/ZUNMHR) multiplies an arbitrary complex matrix C by the complex unitary matrix Q which was determined by F08NSF (CGEHRD/ZGEHRD) when reducing a complex general matrix to Hessenberg form.

2 Specification

```
SUBROUTINE FO8NUF(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C,

LDC, WORK, LWORK, INFO)

ENTRY cunmhr(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C,

LDC, WORK, LWORK, INFO)

INTEGER M, N, ILO, IHI, LDA, LDC, LWORK, INFO

complex A(LDA,*), TAU(*), C(LDC,*), WORK(LWORK)

CHARACTER*1 SIDE, TRANS
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine is intended to be used following a call to F08NSF(CGEHRD/ZGEHRD), which reduces a complex general matrix A to upper Hessenberg form H by a unitary similarity transformation: $A = QHQ^H$. F08NSF represents the matrix Q as a product of $i_{hi} - i_{lo}$ elementary reflectors. Here i_{lo} and i_{hi} are values determined by F08NVF (CGEBAL/ZGEBAL) when balancing the matrix; if the matrix has not been balanced, $i_{lo} = 1$ and $i_{hi} = n$.

This routine may be used to form one of the matrix products

$$QC, Q^HC, CQ \text{ or } CQ^H,$$

overwriting the result on C (which may be any complex rectangular matrix).

A common application of this routine is to transform a matrix V of eigenvectors of H to the matrix QV of eigenvectors of A.

4 References

[1] Golub G H and van Loan C F (1996) Matrix Computations Johns Hopkins University Press (3rd Edition), Baltimore

5 Parameters

1: SIDE — CHARACTER*1

Input

On entry: indicates how Q or Q^H is to be applied to C as follows:

```
if SIDE = 'L', then Q or Q^H is applied to C from the left; if SIDE = 'R', then Q or Q^H is applied to C from the right.
```

Constraint: SIDE = 'L' or 'R'.

2: TRANS — CHARACTER*1

Input

On entry: indicates whether Q or Q^H is to be applied to C as follows:

if TRANS = 'N', then Q is applied to C; if TRANS = 'C', then Q^H is applied to C.

Constraint: TRANS = 'N' or 'C'.

3: M — INTEGER

Input

On entry: m, the number of rows of the matrix C; m is also the order of Q if SIDE = 'L'.

Constraint: M > 0.

4: N — INTEGER

Input

On entry: n, the number of columns of the matrix C; n is also the order of Q if SIDE = 'R'.

Constraint: $N \ge 0$.

5: ILO — INTEGER

Input

6: IHI — INTEGER

Input

On entry: these **must** be the same parameters ILO and IHI, respectively, as supplied to F08NSF (CGEHRD/ZGEHRD).

Constraints:

```
1 \le ILO \le IHI \le M if SIDE = 'L' and M > 0;
 ILO = 1 and IHI = 0 if SIDE = 'L' and M = 0;
 1 \le ILO \le IHI \le N if SIDE = 'R' and N > 0;
 ILO = 1 and IHI = 0 if SIDE = 'R' and N = 0.
```

7: A(LDA,*) — complex array

Input

Note: the second dimension of the array A must be at least max(1,M) if SIDE = 'L' and at least max(1,N) if SIDE = 'R'.

On entry: details of the vectors which define the elementary reflectors, as returned by F08NSF (CGEHRD/ZGEHRD).

8: LDA — INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which F08NUF (CUNMHR/ZUNMHR) is called.

Constraints:

```
LDA \ge max(1,M) if SIDE = 'L', LDA \ge max(1,N) if SIDE = 'R'.
```

9: TAU(*) — complex array

Inpu

Note: the dimension of the array TAU must be at least max(1,M-1) if SIDE = 'L' and at least max(1,N-1) if SIDE = 'R'.

On entry: further details of the elementary reflectors, as returned by F08NSF (CGEHRD/ZGEHRD).

10: C(LDC,*) — complex array

Input/Output

Note: the second dimension of the array C must be at least max(1,N).

On entry: the m by n matrix C.

On exit: C is overwritten by QC or Q^HC or CQ^H or CQ as specified by SIDE and TRANS.

11: LDC — INTEGER Input

On entry: the first dimension of the array C as declared in the (sub)program from which F08NUF (CUNMHR/ZUNMHR) is called.

Constraint: LDC $\geq \max(1,M)$.

12: WORK(LWORK) — complex array

Work space

On exit: if INFO = 0, WORK(1) contains the minimum value of LWORK required for optimum performance.

13: LWORK — INTEGER

Input

On entry: the dimension of the array WORK as declared in the (sub)program from which F08NUF (CUNMHR/ZUNMHR) is called.

Suggested value: for optimum performance LWORK should be at least N \times nb if SIDE = 'L' and at least M \times nb if SIDE = 'R', where nb is the **blocksize**.

Constraints:

LWORK
$$\geq \max(1,N)$$
 if SIDE = 'L',
LWORK $\geq \max(1,M)$ if SIDE = 'R'.

14: INFO — INTEGER

Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed result differs from the exact result by a matrix E such that

$$||E||_2 = O(\epsilon)||C||_2$$

where ϵ is the *machine precision*.

8 Further Comments

The total number of real floating-point operations is approximately $8nq^2$ if SIDE = 'L' and $8mq^2$ if SIDE = 'R', where $q = i_{hi} - i_{lo}$.

The real analogue of this routine is F08NGF (SORMHR/DORMHR).

9 Example

To compute all the eigenvalues of the matrix A, where

$$A = \begin{pmatrix} -3.97 - 5.04i & -4.11 + 3.70i & -0.34 + 1.01i & 1.29 - 0.86i \\ 0.34 - 1.50i & 1.52 - 0.43i & 1.88 - 5.38i & 3.36 + 0.65i \\ 3.31 - 3.85i & 2.50 + 3.45i & 0.88 - 1.08i & 0.64 - 1.48i \\ -1.10 + 0.82i & 1.81 - 1.59i & 3.25 + 1.33i & 1.57 - 3.44i \end{pmatrix},$$

and those eigenvectors which correspond to eigenvalues λ such that $\text{Re}(\lambda) < 0$. Here A is general and must first be reduced to upper Hessenberg form H by F08NSF (CGEHRD/ZGEHRD). The program then calls F08PSF (CHSEQR/ZHSEQR) to compute the eigenvalues, and F08PXF (CHSEIN/ZHSEIN) to compute the required eigenvectors of H by inverse iteration. Finally F08NUF (CUNMHR/ZUNMHR) is called to transform the eigenvectors of H back to eigenvectors of the original matrix A.

9.1 Program Text

Note. The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO8NUF Example Program Text
Mark 16 Release. NAG Copyright 1992.
.. Parameters ..
                NIN, NOUT
INTEGER
PARAMETER
                (NIN=5,NOUT=6)
INTEGER
               NMAX, LDA, LDH, LDZ, LWORK, LDVL, LDVR
                (NMAX=8,LDA=NMAX,LDH=NMAX,LDZ=1,LWORK=64*NMAX,
PARAMETER
                LDVL=NMAX,LDVR=NMAX)
.. Local Scalars ..
real
                 THRESH
INTEGER
                I, IFAIL, INFO, J, M, N
.. Local Arrays ..
complex
                 A(LDA, NMAX), H(LDH, NMAX), TAU(NMAX),
                 VL(LDVL, NMAX), VR(LDVR, NMAX), W(NMAX),
                WORK(LWORK), Z(LDZ,1)
real
                 RWORK (NMAX)
INTEGER
                IFAILL(NMAX), IFAILR(NMAX)
LOGICAL
                 SELECT(NMAX)
CHARACTER
                CLABS(1), RLABS(1)
.. External Subroutines ..
EXTERNAL FO6TFF, XO4DBF, cgehrd, chsein, chseqr, cunmhr
.. Intrinsic Functions ..
INTRINSIC
               real, imag
.. Executable Statements ..
WRITE (NOUT,*) 'FO8NUF Example Program Results'
Skip heading in data file
READ (NIN,*)
READ (NIN,*) N
IF (N.LE.NMAX) THEN
   Read A from data file
   READ (NIN,*) ((A(I,J),J=1,N),I=1,N)
   READ (NIN,*) THRESH
   Reduce A to upper Hessenberg form H = (Q**H)*A*Q
   CALL cgehrd(N,1,N,A,LDA,TAU,WORK,LWORK,INFO)
   Copy A to H
   CALL FO6TFF('General', N, N, A, LDA, H, LDH)
   Calculate the eigenvalues of H (same as A)
   CALL chseqr('Eigenvalues','No vectors',N,1,N,H,LDH,W,Z,LDZ,
               WORK, LWORK, INFO)
   WRITE (NOUT, *)
   IF (INFO.GT.O) THEN
      WRITE (NOUT,*) 'Failure to converge.'
      WRITE (NOUT,*) 'Eigenvalues'
```

```
\texttt{WRITE (NOUT,99999) (' (',real(W(I)),',',imag(W(I)),')',I=1,}\\
             DO 20 I = 1, N
                SELECT(I) = real(W(I)) .LT. THRESH
   20
             CONTINUE
             Calculate the eigenvectors of H (as specified by SELECT),
             storing the result in VR
             CALL chsein('Right', 'QR', 'No initial vectors', SELECT, N, A,
                          LDA, W, VL, LDVL, VR, LDVR, N, M, WORK, RWORK, IFAILL,
                          IFAILR, INFO)
             Calculate the eigenvectors of A = Q * (eigenvectors of H)
             CALL cunmhr('Left','No transpose',N,M,1,N,A,LDA,TAU,VR,LDVR,
                          WORK, LWORK, INFO)
             Print eigenvectors
             WRITE (NOUT, *)
             IFAIL = 0
             CALL XO4DBF('General',' ',N,M,VR,LDVR,'Bracketed','F7.4',
                          'Contents of array \ensuremath{\mathsf{VR'}}, 'Integer', RLABS,
                          'Integer', CLABS, 80, 0, IFAIL)
         END IF
      END IF
      STOP
99999 FORMAT ((3X,4(A,F7.4,A,F7.4,A,:)))
      END
```

9.2 Program Data

```
FO8NUF Example Program Data

4 :Value of N

(-3.97,-5.04) (-4.11, 3.70) (-0.34, 1.01) ( 1.29,-0.86)
( 0.34,-1.50) ( 1.52,-0.43) ( 1.88,-5.38) ( 3.36, 0.65)
( 3.31,-3.85) ( 2.50, 3.45) ( 0.88,-1.08) ( 0.64,-1.48)
(-1.10, 0.82) ( 1.81,-1.59) ( 3.25, 1.33) ( 1.57,-3.44) :End of matrix A

0.0 :Value of THRESH
```

9.3 Program Results